

Outdoor Asset Tracker

Featuring LoRaWAN® AT101

User Guide





Safety Precautions

Milesight will not shoulder responsibility for any loss or damage resulting from not following the instructions of this operating guide.

- The device must not be disassembled or remodeled in any way.
- In order to protect the security of the device, please change the device password when first configuration. Default password is 123456.
- The device is not intended to be used as a reference sensor, and Milesight won't should responsibility for any damage which may result from inaccurate readings.
- Do not place the device close to objects with naked flames.
- ❖ Do not place the device in where the temperature is below/above the operating range.
- Make sure all batteries are newest when install, or battery life will be reduced.

Declaration of Conformity

AT101 is in conformity with the essential requirements and other relevant provisions of the CE, FCC, and RoHS.









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Revision History

Date	Doc Version	Description
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1. Product Introduction

1.1 Overview

AT101 is an exceptional outdoor tracker that utilizes GNSS and Wi-Fi AP MAC Address Scanning to provide highly accurate positioning data. Additionally, it has tilt and temperature sensors for more extensive data collection and application in various scenarios. The device is designed with IP67 and IK09 ratings to cater to different environments.

AT101 collaborates with standard LoRaWAN® gateway and mainstream LoRaWAN® network servers with low power consumption, allowing it to operate for over 15 years with twice-daily reports. By integrating with Milesight LoRaWAN® gateway and Milesight IoT Cloud solution, users can remotely and visually manage all sensor data.

1.2 Features

- Equipped with highly-accurate GNSS positioning and cooperate with Wi-Fi positioning
- Equipped with NTC temperature sensor to enable environment detection
- Built-in 3-axis accelerometer sensor to monitor device tilt status and movement
- Support IP67 and IK09 rating protections for harsh environment application
- Built-in replaceable batteries and works for up to over 15 years without replacement
- Provide integrated structure and anti-theft design for wireless and safe deployment
- Incorporate UV protection to be suitable for outdoor environments.
- Support geofencing for targeted messaging to secure the assets and area
- Multiple and switchable modes provide motion tracking, periodic tracking, and timing tracking
- Store locally 1,300 historical records and support retransmission to prevent data loss
- Equipped with NFC and Bluetooth for easy configuration
- Function well with standard LoRaWAN® gateway and network servers
- Compatible with Milesight IoT Cloud

2. Hardware Introduction

2.1 Packing List





Mitesight
WARRANTY
CARD



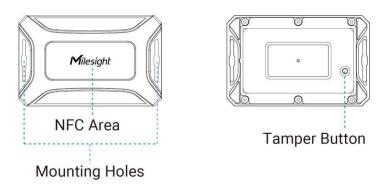


 $1 \times AT101$ $2 \times Mounting$ $1 \times 3M$ Tape $1 \times Warranty$ $1 \times Device$ Kits Card Quick Guide

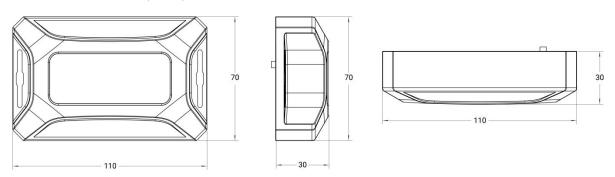


If any of the above items is missing or damaged, please contact your sales representative.

2.2 Hardware Overview



2.3 Dimensions (mm)



2.4 Power Button

AT101 can be switched on/off via NFC. Besides, users can use internal power button to switch on/off and reset the device manually.

Function	Action	LED Indication
Switch On	Press and hold the button for more than 3 seconds.	Off → On
Switch Off	Press and hold the button for more than 3 seconds.	On → Off
Reset	Press and hold the button for more than 10 seconds.	Quickly Blinks
Check		Light On: Device is on
On/Off Status	Quickly press the power button.	Light Off: Device is off



3. Operation Guide

3.1 NFC&Bluetooth Configuration

AT101 can be configured via NFC or Bluetooth.

NFC Configuration:

- 1. Download and install **Milesight ToolBox** App from Google Play or App Store.
- 2. Open Milesight ToolBox App, tap NFC Read button and enable NFC on the smartphone.
- 3. Attach the smartphone with NFC area to the device to read the basic information.



4. Basic information and settings of devices will be shown on ToolBox if it's recognized successfully. You can switch on/off, read and write the device by tapping the button on the Apps. In order to protect the security of devices, password validation is required when configuring via unused phone. The default password is **123456**.

Status		Maintenance
SN	67450)19027970000
Model		AT101-470M
Device EUI	24E12	24745D190279
Firmware Version		V1.1
Hardware Version		V1.1
Device Status		ON
Join Status		Activated
Reading Mode		NFC

Note:

- 1) Ensure the location of smartphone NFC area and it's recommended to take off phone case.
- 2) If the smartphone fails to read/write configurations via NFC, keep the phone away and back to try again.
- 3) AT101 can also be configured by dedicated NFC reader provided by Milesight IoT or you can



configure it via TTL interface inside the device.

Bluetooth Configuration:

- 1. Download and install **Milesight ToolBox** App from Google Play or App Store.
- 2. Enable Bluetooth on the smartphone, then open **Milesight ToolBox** App.
- 3. Tap **BLE Read** button to scan the devices and select the one to connect. The default Bluetooth name is AT101-XXXXXXXX(5th to 11st of device SN) and the default login password is 123456. If the device is off, please turn on the device via NFC first.



4. Basic information and settings of devices will be shown on ToolBox if it's connected successfully. You can read and write the device by tapping the button on the Apps. In order to protect the security of devices, password validation is required when configuring via unused phone.

Status	Setting	Maintenance
SN	6745	D19027970000
Model		AT101-470M
Device EUI	24E12	24745D190279
Firmware Version		V1.1
Hardware Version		V1.1
Device Status		ON
Join Status		Activated
Reading Mode		BLE .il

Note:

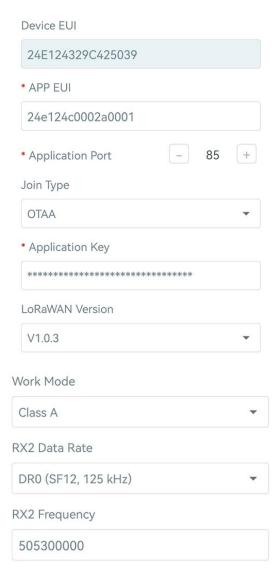
- 1) If the Bluetooth password is entered for over 1 min, please re-enter the password.
- 2) The waiting interval will be increased gradually if the failed password attempts reach for 5 times continuously.
- 3) The Bluetooth connection will be terminated if there's no data interaction within 3 minutes. It



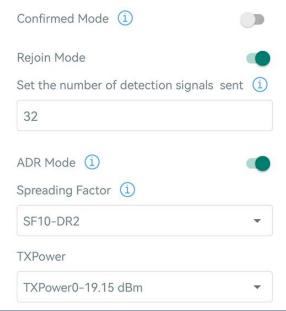
will request to connect again.

4) The device can connect to only one phone via Bluetooth. For example, if the device is connected to smart phone A via Bluetooth, the connection will be terminated after it is connected to smartphone B.

3.2 LoRaWAN Settings

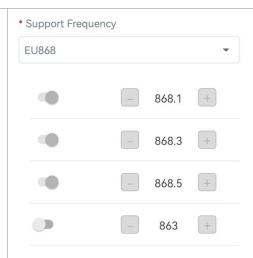






Parameters	Description
Device EUI	Unique ID of the device which can also be found on the label.
App EUI	Default App EUI is 24E124C0002A0001.
Application Port	The port used for sending and receiving data, default port is 85.
Join Type	OTAA and ABP mode are available.
Application Key	Appkey for OTAA mode, default is 5572404C696E6B4C6F52613230313823.
Device Address	DevAddr for ABP mode, default is the 5 th to 12 th digits of SN.
Network Session Key	Nwkskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.
Application Session Key	Appskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.
LoRaWAN Version	V1.0.2, V1.0.3, V1.0.4 are available.
Work Mode	It's fixed as Class A.
RX2 Data Rate	RX2 data rate to receive downlinks.
RX2 Frequency	RX2 frequency to receive downlinks. Unit: Hz
Channel	Enable or disable the frequency to send uplinks.



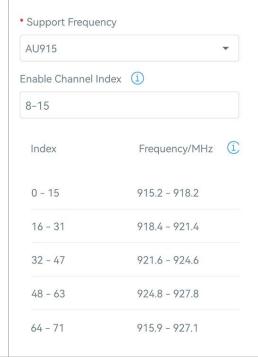


If frequency is one of CN470/AU915/US915, enter the index of the channel that you want to enable and make them separated by commas.

Examples:

- 1, 40: Enabling Channel 1 and Channel 40
- 1-40: Enabling Channel 1 to Channel 40
- 1-40, 60: Enabling Channel 1 to Channel 40 and Channel 60
- All: Enabling all channels

Null: Indicates that all channels are disabled



Spread Factor	If ADR is disabled, the device will send data via this spread factor.	
Confirmed Mode	If the device does not receive ACK packet from network server, it will resend	
	data once.	
Rejoin Mode	Reporting interval ≤ 35 mins: the device will send a specific number of	
	LinkCheckReq MAC packets to the network server every reporting interval or	



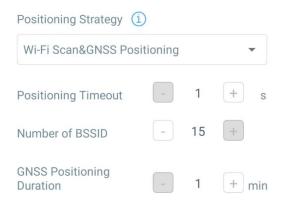
	2*reporting interval to validate connectivity; If there is no response, the device will re-join the network.
	Reporting interval > 35 mins: the device will send a specific number of
	LinkCheckReq MAC packets to the network server every reporting interval to
	validate connectivity; If there is no response, the device will re-join the
	network.
Set the number of	When rejoin mode is enabled, set the number of LinkCheckReq packets sent.
packets sent	Note: the actual sending number is Set the number of packets sent + 1.
ADR Mode	Allow network server to adjust data rate of the device.
Tx Power	Transmit power of device.

Note:

- 1) Please contact sales for a device EUI list if there are many units.
- 2) Please contact sales if you need random App keys before purchase.
- 3) Select OTAA mode if you use Milesight IoT cloud to manage devices.
- 4) Only OTAA mode supports rejoin mode.

3.3 Positioning Settings

Go to **Device > Setting > Positioning Settings** to set the positioning strategy and related settings.



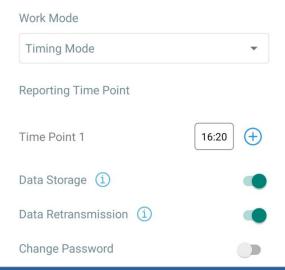
Parameters	Description
	Select the strategy for each time's positioning.
	GNSS Positioning: locate the device position via GNSS. This mode is used
Dooitioning	on outdoor open environment.
Positioning	Wi-Fi Scan: locate the device position via Wi-Fi scan. This mode is used on
Strategy	crowded streets or indoor environment.
	Wi-Fi Scan&GNSS Positioning: locate the device position via Wi-Fi scan
	first; if this failed, switch to GNSS to locate again. This mode will consume



	the most power.	
Note: When Wi-Fi scan is failed, the device will still upload the Wi-Fi s		
	results.	
Positioning	When the device fails to scan for a sufficient numbers of Wi-Fi BSSID	
Timeout	within this timeout, it will stop scanning.	
Number of BSSID	The number of BSSID which the device needs to upload each positioning.	
GNSS Positioning	When the device fails to get location via GNSS within this duration, it will	
Duration	stop locating. Default: 3 mins, range: 1~5 mins.	

3.4 General Settings

Go to **Device > Setting > General Settings** to change the reporting interval, etc.



Parameters	Description
Work Mode	Select the work mode to report location data to network server.
Data Storage	Disable or enable reporting GNSS data storage locally. (see section 3.5.2 to export data)
Data Retransmission	Disable or enable data retransmission. (see section $3.5.3$)
Change Password	Change the NFC or Bluetooth password for ToolBox App or software to access this device.

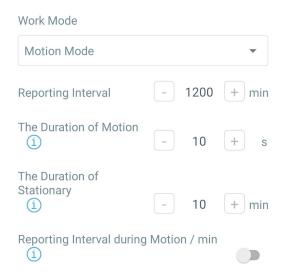
Periodic Mode: report data periodically.





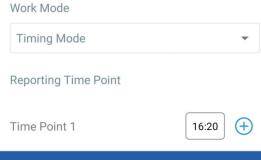
Parameters	Description
Reporting Interval	The interval to locate the device position. After located, the device will
	report the data to network server. Default: 1440 mins, range: 1~1440 mins

Motion Mode: report data according to device motion status.



Parameters	Description		
	The interval to locate the device position when device is in stationary. After		
Reporting Interval	located, the device will report the data to network server. Default: 1440		
	mins, range: 1~1440 mins		
The duration of	/hen device is detected to move beyond this duration, it will locate the		
Motion	device position and upload a location data packet.		
The duration of	When device is detected to stop moving beyond this duration, it will locate		
stationary	the device position and upload a location data packet.		
Report Interval	The interval to locate the device position when device is in motion. After		
during Motion/Min	located, the device will report the data to network server.		

Timing Mode: report data as scheduled. Ensure the device time is synced via ToolBox before switching to this mode.



Parameters Description



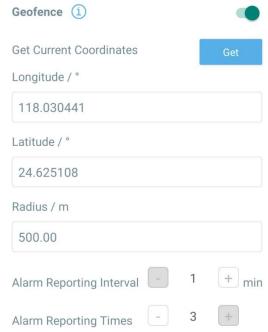
Reporting Time	One device can set at most 5 time points of every day to report data on
Point	Timing Mode.

3.5 Advanced Settings

3.5.1 Threshold Settings Geofence:

When GNSS positioning is enabled, AT101 supports to set a round geofence range. AT101 will detect whether the location is within the radius range of preset coordinates. If the device is out of the range, it will upload threshold alarm packets; if it returns back to the range, it will upload a threshold alarm dismiss packet.

Note: after Geofence is enabled, it only works after next positioning.



Parameters	Description					
Get Current						
Coordinates	Get current device coordinates for reference.					
	The geofence radius based on the coordinates.					
Dadina (aa	Note: The alarm is activated when the device is located 10 meters further					
Radius/m	than the set radius value; the alarm is dismiss when the device is located					
	10 meters closer than the set radius value.					
Alarm Reporting	After the threshold is triggered, the device will locate according to this					
Interval	reporting interval to detect if the threshold is still triggered.					
Alarm Reporting	Alaman and the state of the sta					
Times	Alarm packet reporting times if the threshold is still triggered.					



Tilt Threshold:

When the offset angle of any axis is more than 20° based on initial surface, the device will upload a tilt alarm packet; when offset angle of all 3 axis is within 20° based on initial surface, the device will upload an alarm dismiss packet.



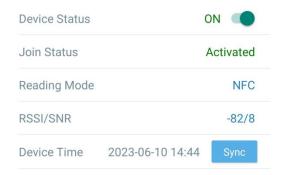
Parameters	Description
Deflection Angle	Enable or disable to upload tilt alarm and alarm dismiss packets.
Setting	Click to set current position of device as initial position.
Clear	Change the initial position back to (0.00°, 0.00°, -90.00°)

Note: after writing **Setting** or **Clear** configuration, click **Read** to read the device to check if the initial position changes successfully.

3.5.2 Data Storage

AT101 sensor supports storing 1,300 data records locally and export data via ToolBox App. The device will record the GNSS data according to reporting interval even not joining to network. It will not record Wi-Fi scanning data locally.

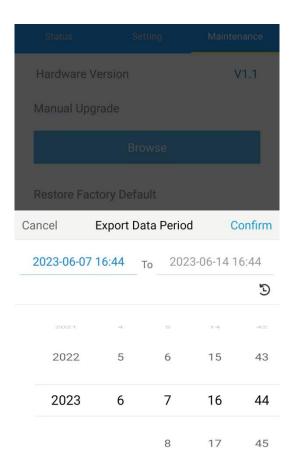
1. Go to **Device > Status** of ToolBox App to click **Sync** to sync the device time.



2. Go to **Device > Setting > General Settings** of ToolBox App to enable data storage feature.



3. Go to **Device > Maintenance** of ToolBox App, click **Export**, then select the data time period and click **Confirm** to export data. The maximum export data period on ToolBox App is 14 days.



4. Click **Data Cleaning** to clear all stored data inside the device.



3.5.3 Data Retransmission

AT101 sensor supports data retransmission to ensure the network server can get all data even if network is down for some times. There are two ways to get the lost data:

- Network server sends downlink commands to enquire the historical data for specifying time range, refer to section <u>5.3</u>.
- When network is down if no response from LinkCheckReq MAC packets for a period of time, the device will record the network disconnected time and re-transmit the lost data after device re-connects the network.

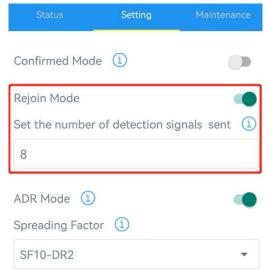
Here are the steps for retransmission:



1. Go to **Device > Setting > General Settings** to enable data storage and data retransmission feature.



2. Go to **Device > Settings > LoRaWAN Settings** to enable rejoin mode feature and set the number of packets sent. Take below as example, the device will send LinkCheckReq MAC packets to the network server regularly to check if the network is disconnected; if there is no response for 8+1 times, the join status will change to de-active and the device will record a data lost time point(the time to join the network).



3. After the network connected back, the device will send the lost data from the point in time when the data was lost according to the data re-transmission reporting interval.

Note:

- 1) If the device is reboot or re-powered when data retransmission is not completed, the device will re-send all retransmission data again after device is reconnected to the network.
- 2) If the network is disconnected again during data retransmission, it will only send the latest disconnection data.
- 3) The retransmission data format is started with "20ce", please refer to section 5.3.
- 4) Data retransmission will increase the uplinks and shorten the battery life.

3.6 Maintenance

3.6.1 Upgrade

- 1. Download firmware from Milesight website to your smartphone.
- 2. Open Toolbox App, go to Device > Maintenance and click Browse to import firmware and



upgrade the device.

Note:

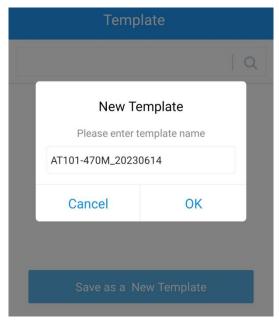
- 1) Operation on ToolBox is not supported during a firmware upgrade.
- 2) Only Android version ToolBox supports the upgrade feature.

		Maintenance		
SN	6745D	19027970000		
Model		AT101-470M		
Firmware Version	n	V1.1		
Hardware Versio	n	V1.1		
Manual Upgrade				
Browse				

3.6.2 Backup

AT101 supports configuration backup for easy and quick device configuration in bulk. Backup is allowed only for devices with the same model and LoRaWAN® frequency band.

- 1. Go to **Template** page on the App and save current settings as a template. You can also edit the template file.
- 2. Select one template file which saved in the smartphone and click **Write**, then attach to another device to write configuration.



Note: Slide the template item left to edit or delete the template. Click the template to edit the



configurations.

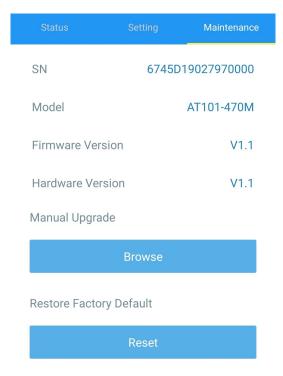
	Template					
			Q			
e: 2023	3-03-08 09:33:28	Edit	Delete			
>_	EM400-MUD Last Modified Time: 2023-03-	08 09:33:46				
>_	EM400-UDL_20230308 Last Modified Time: 2023-03-08 09:35:10					

3.6.3 Reset to Factory Default

Please select one of following methods to reset device:

Via Hardware: Hold on power button (internal) for more than 10s.

Via ToolBox App: Go to Device > Maintenance to click Reset.

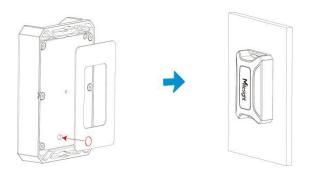


4. Installation

Fixed by 3M Tape:

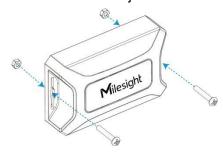
Paste 3M tape to the back of device, tear the other side and attach it to the measured object. (Align the hole with the tamper button when pasting)





Fixed by Mounting Kits:

- 1. Drill two holes on the measured object according to the location of device mounting holes.
- 2. Put the device on the object, fix it to the object with two mounting screws and and screw the bolts into the mounting screws from the other side of the object.



5. Device Payload

All data are based on following format (HEX), the Data field should follow little-endian:

Channel1	Type1	Data1	Channel2	Type2	Data2	Channel 3	
1 Byte	1 Byte	N Bytes	1 Byte	1 Byte	M Bytes	1 Byte	

For decoder examples please find files on https://github.com/Milesight-IoT/SensorDecoders.

5.1 Uplink Data

Channel	Туре	Description
	01(Protocol Version)	01=>V1
	09 (Hardware Version)	01 40 => V1.4
ff	0a (Software Version)	01 14 => V1.14
"	0b (Power On)	Device is on
	Of (Device Type)	00: Class A, 01: Class B, 02: Class C
	16 (Device SN)	16 digits
01	75(Battery Level)	UINT8, Unit: %
03	67 (Temperature)	INT16, Unit: °C
04	88 (GNSS Location) Byte 1-4: latitude*1000000	

		Byte 5-8: longitude*1000000	
		Byte 9: Geofence + motion status	
		Geofence(Bit 7-4): 0=within geofence,	
		1=out of geofence, 2=geofence disabled,	
		3=unknown	
		Motion status (Bit 3-0): 0=unknown, 1=start	
		moving, 2=in motion, 3=stop moving	
		Note: If the device fails to get GNSS data,	
		the latitude or longitude will show	
		FFFFFFF.	
05	00 (Device Position)	00: Normal (Offset angle < 20°) 01: Tilt (Offset angle ≥ 20°)	
		9 Bytes,	
		Byte 1: id(00~FF), it will plus one every scan	
		Byte 2-7: Wi-Fi BSSID (MAC address)	
	d9 (Wi-Fi Location)	Byte 8: RSSI, unit: dBm, INT8	
06		Byte 9: Motion status, 00=unknown,	
		01=start moving, 02=in motion, 03=stop	
		moving	
		Note: If the device fails to get scan results,	
		it will upload all as FF.	
		00: Device installed (Tamper button pressed)	
		01: Device un-installed (Tamper button	
07	00(Tamper Status)	released)	
		Note: tamper status packet is fixed as	
		confirmed packet.	
		Temperature (2 Bytes) + Alarm Status(1	
		Byte)	
83	67(Temperature)	Temperature: unit °C	
03	07 (Terriperature)	Alarm Status:	
		00 -Alarm dismiss	
		01 -Alarm	
84	88 (GNSS Location)	Byte 1-4: latitude*1000000	
04	OU (GINGS LOCATION)	Byte 5-8: longitude*1000000	



Ву	te 9: Geofence + motion status
Ge	ofence(Bit 7-4): 0=within geofence,
1=	out of geofence, 2=geofence disabled,
3=	unknown
Mo	otion status (Bit 3-0): 0=unknown, 1=start
mo	oving, 2=in motion, 3=stop moving
No	te: If the device fails to get GNSS data,
the	e latitude or longitude will show
FF	FFFFF.

Examples:

1. Device information: report once whenever join the network.

ff0bff ff0101 ff166745d19027970000 ff090110 ff0a0101 ff0f00					
Channel	Туре	Value	Channel	Туре	Value
ff	0b (Power On)	ff (Reserved)	ff	01 (Protocol Version)	01 (V1)
Channel	Туре	Value	Channel	Туре	Value
ff	16 (Device SN)	745d190279 70000	ff	09 (Hardware version)	0110 (V1.1)
Channel	Туре	Value	Channel	Туре	Value
ff	0a (Software version)	0101 (V1.1)	ff	Of (Device Type)	00 (Class A)

2. GNSS uplink: report when position strategy is GNSS positioning.

017564 03670a01 050001 0488debc770108ff080720					
Channel	Туре	Value	Channel	Туре	Value
01	75	64 =>	03	67	f8 00 => 00 f8
01	(Battery)	100%	03	(Temperature)	= 248 * 0.1 =24.8 °C
Channel	Туре	Value	Channel	Туре	Value
					Latitude:
		01=Tilt	04	88(Location)	debc7701=>01 77
	00 (Device Position)				bc
					de=24624350/1000
05					000=24.624350
03					Longitude:
	Position				08ff0807=>07 08 ff
					08=118030088/100
					0000=118.030088
					20=Geofence



		disable, motion
		unknown

3. Wi-Fi scan uplink: report when position strategy is Wi-Fi scan.

017564 03671201 050001 06d90024e124f5b797b300 06d90024e124ff0004c800 06d90024e124f319a8c100 06d9000650c20eaa8dc500 06d90024e124f721c4b900

Channel	Туре	Value	Channel	Туре	Value
01	75 (Battery)	64 => 100%	03	67 (Temperatu re)	12 01 => 01 12 = 274 * 0.1 =27.4 °C
Channel	Type	Value	Channel	,	Value
Channel	Туре	value	Channel	Туре	
05	00 (Device Position)	01=Tilt	06	d9 (Wi-Fi Location)	ID:00 BSSID: 24e124f5b797 Signal: b3=-77 dBm 00=unknown
Channel	Туре	Value	Channel	Туре	Value
06	d9 (Wi-Fi Location)	ID:00 BSSID: 24e124ff000 4 Signal: c8=-56 dBm 00=unknown	06	d9 (Wi-Fi Location)	ID:00 BSSID: 24e124f319a8 Signal: c1=-63 dBm 00=unknown
Channel	Туре	Value	Channel	Туре	Value
06	d9 (Wi-Fi Location)	ID:00 BSSID: 0650c20eaa 8d Signal: c5=-59 dBm 00=unknown	06	d9 (Wi-Fi Location)	ID:00 BSSID: 24e124f721c4 Signal: b9=-71 dBm 00=unknown

4. Geofencing threshold alarm: when geofence is enabled, report when device goes out of geofence or goes into geofence.

	84887dbe7701e600090711			
Channel Type Value				
		Latitude: 7dbe7701=>01 77 be		
		7d=24624765/1000000=24.624765		
84	88(Location)	Longitude: e6000907=>07 09 00		
		e6=118030566/1000000=118.030566		
		11=Out of Geofence, start moving		



5. Tamper alarm: report tamper status and last location when tamper status changes. The location information are GNSS coordinates or Wi-Fi scan results depending on positioning strategy.

070001 0488fffffffffff30					
Channel	Туре	Value	Channel	Туре	Value
	00/Tampar	01=			Latitude/longitud
07	00(Tamper 01= Status) unistalled		04	88(Location)	e: FFFFFFF
				30=unknown	

6. Tilt threshold alarm: report when deflection angle is enabled and device position changes.

050001			
Channel	Туре	Value	
05	00(Device Position)	01=Tilt	

7. Temperature threshold alarm: report temperature and last location when the abrupt change of temperature is greater than 5 °C. The location information are GNSS coordinates or Wi-Fi scan results depending on positioning strategy.

	8367220101 0488fffffffffff30					
Channel	Туре	Value	Channel	Туре	Value	
83	67 (Temperat ure)	Temperature: 22 01 =>01 22 = 290 * 0.1 = 29°C Alarm Status: 01= Alarm	04	88(Locatio n)	Latitude/longitud e: FFFFFFF 30=unknown	

5.2 Downlink Commands

AT101 supports downlink commands to configure the device. Application port is 85 by default.

Channel	Туре	Description
	10 (Reboot)	ff
	17 (Time Zone)	2 Bytes, UTC timezone * 10
		00: GNSS Positioning
	71 (Positioning Strategy)	01: Wi-Fi Scan
ff		02: Wi-Fi Scan&GNSS Positioning
III	3c (GNSS Positioning Duration)	1 Byte, unit: min
		3 Bytes,
	2d (Wi-Fi Scan)	Byte 1: 00
		Byte 2: Number of BSSID
		Byte 3: Positioning Timeout , unit:s

00: Periodic Mode 01: Motion Mode 02: Timing Mode 3 Bytes, Byte 1: 00=Periodic mode reporting interval, 01= Motion mode reporting interval, 01= Motion mode reporting interval byte 2-3: reporting interval time, unit: min 3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: 01=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 6a (Data Retransmission Interval) 7e (Geofence Setting) 7e (Geofence Setting) 7e (Geofence Coordinates) 8 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1: 4: latitude*1000000 Byte 5-8: longitude*1000000			
02: Timing Mode 3 Bytes, Byte 1: 00=Periodic mode reporting interval, 01= Motion mode reporting interval, 01= Motion mode reporting interval, 13 (Report Interval during Motion) 3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 00: disable, 01: enable 00: disable, 01: enable 3 Bytes 6a (Data Retransmission) Interval) 9 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00*, 0.00*,			00: Periodic Mode
3 Bytes, Byte 1: 00=Periodic mode reporting interval, 01= Motion mode reporting interval, 13 (Report Interval during Motion) 3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00*, 0.00*,		66 (Work Mode)	01: Motion Mode
Byte 1: 00=Periodic mode reporting interval, 01= Motion mode reporting interval, Byte 2-3: reporting interval time, unit: min 13 (Report Interval during Motion) 13 (Report Interval during Motion) 13 (Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) O0: disable, 01: enable 3 Bytes 6a (Data Retransmission) Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1: 4: Iatitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			02: Timing Mode
3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: reporting interval time, unit: min 3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Ba(Reporting Time Point) Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) Ou: disable, 01: enable 69 (Data Retransmission) Byte 2: 3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1: 01=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			3 Bytes,
01= Motion mode reporting interval Byte 2-3: reporting interval time, unit: min 3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, 58 (Duration of Motion and Stationary) Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*1000000 fe: set the initial position to (0.00*, 0.00*,		On (Departing Interval)	Byte 1: 00=Periodic mode reporting interval,
3 Bytes, Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, 58 (Duration of Motion and Stationary) Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) O0: disable, 01: enable 3 Bytes 6a (Data Retransmission Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		8e (Reporting interval)	01= Motion mode reporting interval
13 (Report Interval during Motion) Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, 58 (Duration of Motion and Stationary) Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, 8a(Reporting Time Point) Byte 2:-3: minute 68 (Data Storage) 69 (Data Retransmission) Interval) 7e (Geofence Setting) 7e (Geofence Setting) 88 (Geofence Coordinates) 89 (Geofence Radius) 89 (Geofence Radius) Bytes: Radius*100, unit: m ff: set current position to (0.00°, 0.00°,			Byte 2-3: reporting interval time, unit: min
Motion) Byte 1: 00 = Disable; 01 = Enable Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) Interval) 7e (Geofence Setting) 7e (Geofence Setting) 89 (Geofence Coordinates) 89 (Geofence Radius) 89 (Geofence Radius) Byte 1: 00 = Disable; 01 = stationary Byte 2: 05 Byte 1: 00 = Disable; 01 = stationary Byte 2: 05 Byte 2: 05 Byte 2: 05 Byte 2: 05 Byte 3: 4: burstion and interval from 00~04 Byte 2: 3: interval time, unit: srange: 30~1200s (600s by default) 4 Bytes, Byte 1: 00 = disable, 01 = enable Byte 2: 3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1: 4: latitude*1000000 Byte 5-8: longitude*1000000 Fyre 5-8: longitude*1000000 Byte 5-8: longitude*1000000		10 (Donort Interval during	3 Bytes,
Byte 2-3: report interval, unit: min 4 Bytes, Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, 8a(Reporting Time Point) Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) Interval) 7e (Geofence Setting) 7e (Geofence Coordinates) 88 (Geofence Radius) 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position to (0.00*, 0.00°, fe: set the initial position to (0.00*, 0.00°,		, .	Byte 1: 00 = Disable; 01 = Enable
Stationary) Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, 8a(Reporting Time Point) Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) Interval) 7e (Geofence Setting) 7e (Geofence Coordinates) 88 (Geofence Radius) 89 (Geofence Radius) Byte 1: 00=motion, 01=stationary Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 00: disable, 01: enable 3 Bytes Byte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		Motion)	Byte 2-3: report interval, unit: min
Byte 2: 05 Byte 3-4: duration, unit: s 3 Bytes, 8a(Reporting Time Point) Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 6a (Data Retransmission Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00-disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			4 Bytes,
Byte 3-4: duration, unit: s 3 Bytes, 8a(Reporting Time Point) Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 6a (Data Retransmission) Byte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, 88 (Geofence Coordinates) Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		58 (Duration of Motion and	Byte 1: 00=motion, 01=stationary
3 Bytes, Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 6a (Data Retransmission Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		Stationary)	Byte 2: 05
8a(Reporting Time Point) Byte 1: time point from 00~04 Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 8ytes 8yte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, 88 (Geofence Coordinates) 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			Byte 3-4: duration, unit: s
Byte 2-3: minute 68 (Data Storage) 00: disable, 01: enable 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 8yte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, 88 (Geofence Coordinates) 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			3 Bytes,
68 (Data Storage) 69 (Data Retransmission) 00: disable, 01: enable 3 Bytes 6a (Data Retransmission Interval) Byte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, 88 (Geofence Coordinates) 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		8a(Reporting Time Point)	Byte 1: time point from 00~04
69 (Data Retransmission) 00: disable, 01: enable 3 Bytes Byte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			Byte 2-3: minute
3 Bytes 6a (Data Retransmission Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		68 (Data Storage)	00: disable, 01: enable
6a (Data Retransmission Interval) Byte 1: 00 Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		69 (Data Retransmission)	00: disable, 01: enable
Interval) Byte 2-3: interval time, unit:s range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		·	3 Bytes
range: 30~1200s (600s by default) 4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,			Byte 1: 00
4 Bytes, Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,			Byte 2-3: interval time, unit:s
Byte 1: 00=disable, 01=enable Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) 62 (Set Initial Position)			range: 30~1200s (600s by default)
Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, 88 (Geofence Coordinates) Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,			4 Bytes,
Byte 2-3: Alarm reporting interval, unit: min Byte 4: Alarm reporting times 8 Bytes, 88 (Geofence Coordinates) Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,		7a (Coofense Setting)	Byte 1: 00=disable, 01=enable
88 (Geofence Coordinates) 89 (Geofence Radius) 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m 62 (Set Initial Position) 8 Bytes, Byte 1-4: latitude*1000000 8 Byte 5-8: longitude*1000000 4 Bytes: Radius*100, unit: m ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°,		7e (Georence Setting)	Byte 2-3: Alarm reporting interval, unit: min
88 (Geofence Coordinates) Byte 1-4: latitude*1000000 Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,			Byte 4: Alarm reporting times
Byte 5-8: longitude*1000000 89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,			8 Bytes,
89 (Geofence Radius) 4 Bytes: Radius*100, unit: m ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,		88 (Geofence Coordinates)	Byte 1-4: latitude*1000000
ff: set current position as initial position 62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,			Byte 5-8: longitude*1000000
62 (Set Initial Position) fe: set the initial position to (0.00°, 0.00°,		89 (Geofence Radius)	4 Bytes: Radius*100, unit: m
			ff: set current position as initial position
-90.00°)		62 (Set Initial Position)	fe: set the initial position to (0.00°, 0.00°,
			-90.00°)



87 (Tamper Alarm)	00 = Disable; 01 = Enable
8f (Bluetooth)	00 = Disable; 01 = Enable

Example:

1. Set time zone as UTC-2.

	ff17ecff				
Channel	Туре	Value			
ff	££ 17	ec ff => ff ec = -20			
11	17	the time zone is UTC-2			

2. Set position strategy as GNSS positioning.

ff7100			
Channel	Туре	Value	
ff	71 (Positioning Strategy)	00: GNSS Positioning	

3. Set periodic mode reporting interval as 1200 minutes.

ff8e00b004				
Channel	Туре	Value		
tt	8e (Reporting Interval)	00=Periodic mode reporting interval		
ff		b0 04 => 04 b0 = 1200 minutes		

4. Reboot the device.

ff10ff			
	Channel	Туре	Value
	ff	10 (Reboot)	ff

5. Set report time point as 20:00.

ff8a04b004			
Channel	Туре	Value	
ff 8	Oo/Donorting Time Doint)	Time point: 04	
11	8a(Reporting Time Point)	b0 04=>04 b0=1200 minutes=20:00	

6. Set the geofence coordinates.

ff88 7dbe7701e6000907			
Channel Type		Value	
		Latitude: 7dbe7701=>01 77 be	
ff	88 (Geofence Coordinates)	7d=24624765/1000000=24.624765 Longitude: e6000907=>07 09 00	
11	86 (Georetice Coordinates)		
		e6=118030566/1000000=118.030566	



5.3 Historical Data Enquiry

AT101 supports sending downlink commands to enquire historical data for specified time point or time range. Before that, ensure the device time is correct and data storage feature was enabled to store the data.

Command format:

Channel	Туре	Description
fd	6b (Enquire data in time point)	4 Bytes, unix timestamp
£J	6c (Enquire data in time range)	Start time (4 bytes) + End time (4 bytes),
fd		Unix timestamp
fd	6d (Stop query data report)	ff
		3 Bytes,
	(/D	Byte 1: 01
ff	6a (Report Interval)	Byte 2: interval time, unit: s,
		range: 30~1200s (60s by default)

Reply format:

Channel	Туре	Description	
	6b/6c	00: data enquiry success	
fc		01: time point or time range invalid	
		02: no data in this time or time range	
	(11)	Data time stamp (4 Bytes) + Longitude (4	
20	ce (Historical Data)	Bytes)+ Latitude (4 Bytes)	

Note:

- 1. The device only uploads no more than 300 data records per range enquiry.
- 2. When enquiring the data in time point, it will upload the data which is the closest to the search point within the reporting interval range. For example, if the device's reporting interval is 10 minutes and users send command to search for 17:00's data, if the device find there is data stored in 17:00, it will upload these data. If not, it will search for data between 16:50 to 17:10 and upload the data which is the closest to 17:00.

Example:

1. Enquire historical data between 2023/6/15 15:45:00 to 2023/6/15 15:55:00.

fd6c 7cc18a64 d4c38a64			
Channel Type		Value	
fd	6c (Enquire data in time range)	Start time: 7cc18a64=> 648ac17c = 1686815100s =2023/6/15 15:45:00 End time: d4c38a64 => 648ac3d4 =	



1686815700s =2023/6/15 15:55:00

Reply:

fc6c00		
Channel	Туре	Value
fc	6c (Enquire data in time range)	00: data enquiry success

20ceccc28a64e60009077dbe7701			
Channel	Туре	Time Stamp	Value
	ce (Historical Data)		Longitude: e6000907=>07 09
			00
		ccc28a64 => 648ac2cc	e6=118030566/1000000=11
20		=> 1686815436s	8.030566
		= 2023-6-15 15:50:36	Latitude: 7dbe7701=>01 77
			be 7d=24624765/1000000
			=24.624765

